

IMPLEMENTATION OF KALMAN FILTER ALGORITHM TO OPTIMIZE THE CALCULATION OF ULTRASONIC SENSOR DISTANCE VALUE IN HOOKE LAW PROPS SYSTEM.

Title	IMPLEMENTATION OF KALMAN FILTER ALGORITHM TO OPTIMIZE THE CALCULATION OF ULTRASONIC SENSOR DISTANCE VALUE IN HOOKE LAW PROPS SYSTEM.
Abstract	
Authors	U Pratiwi, I Fadli, WT Cahyanto
Journal Name	Eastern-European Journal of Enterprise Technologies, 2024
Publish Year	2024
Citation	(not set)
Url	<a +intitle:"implementation="" algorithm="" calculation="" distance="" filter="" hooke="" href="https://scholar.google.com/scholar?q=" in="" kalman="" law="" of="" optimize="" props="" sensor="" system.""="" the="" to="" ultrasonic="" value="">https://scholar.google.com/scholar?q="+intitle:"IMPLEMENTATION OF KALMAN FILTER ALGORITHM TO OPTIMIZE THE CALCULATION OF ULTRASONIC SENSOR DISTANCE VALUE IN HOOKE LAW PROPS SYSTEM."
Author	WAHYU TRI CAHYANTO, S.Si, M.Si, Ph.D