

## Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot

<b>Title</b>	Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot
<b>Abstract</b>	
<b>Authors</b>	S Ma&#39;arif, DA Susanti, M Malik
<b>Journal Name</b>	Proceeding of International Conference on Sustainable Engineering and&#8230;, 2022
<b>Publish Year</b>	2022
<b>Citation</b>	1
<b>Url</b>	<a for="" hexapod="" href="https://scholar.google.com/scholar?q=+intitle:" implementation="" inverse="" kinematics="" method="" of="" on="" robot"="" self-moving="">https://scholar.google.com/scholar?q=+intitle:"Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot"</a>
<b>Author</b>	Dr DYAH SUSANTI