## Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot

Title	Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot
Abstract	
Authors	S Ma'arif, DA Susanti, M Malik
Journal Nam	e Proceeding of International Conference on Sustainable Engineering and …, 2022
Publish Year	2022
Citation	1
Url	https://scholar.google.com/scholar?q=+intitle:"Implementation of Inverse Kinematics Method for Self-Moving on Hexapod Robot"
Author	Dr DYAH SUSANTI